

2)

Cell decomposition approaches

Partition ~~the~~ Ctree into a

Note Title

1/26/2010

set of non-overlapping regions, called

cells where union in tree. Build an adjacency relationship between cell -> cell if a connectivity graph where

nodes are cells and edges between

no edge represent if the current boundary

cells share a boundary. A sequence
of adjacent cells coming from top to bottom

demonstrates a [channel]. A path can
be fractioned from the channel.

What is a cell?

1) generally should be a simple shape; so
"Convex" Hot connecting two pts within
↓
a cell is easy.

2f. line

2) adjacency relationship should be
relatively easy to talk; construct

A part carrying the powerdry should be eng.

Types of cell decompr.:

factory
factory comb. D resolution comb.

approximate : Cell shapes are pre-def.
inh. level
self run.

2) exact : Cell shape is determined
by certain unified mesh
in Cfree :

harder
more
efficed
for low
diss. expow

will lead to complex alg. but

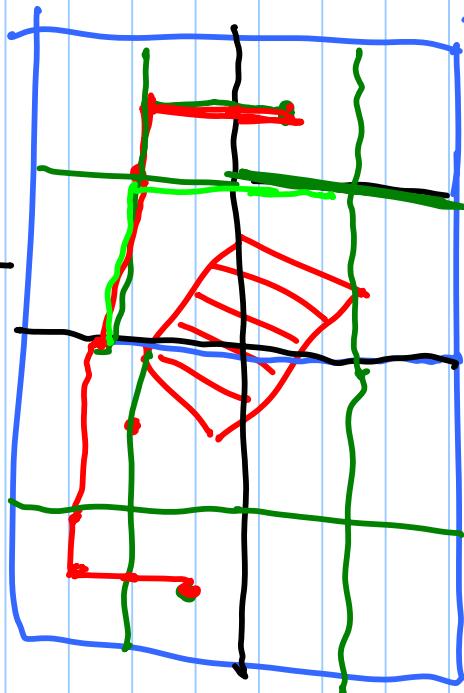
probably more complex

computation are needed

polygona| trapezoidal decom| fcr

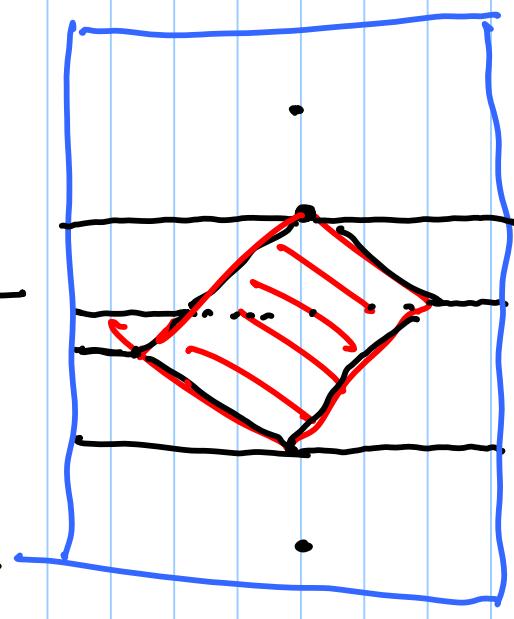
polygona| c-spall.

Ridge



resolution cm
comp| cut

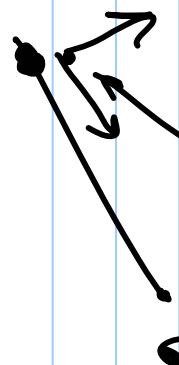
complete alg.



Non-trivial Case : moving a ladder

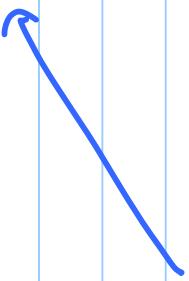
F_p or α in plane
in a polygonal environment

P



General Core : semi-algebraic

acts



Recall they are described by boolean
→ rational coeffs.
Comb. of polynomial inequalities.

→ (obs / robot surfaces)

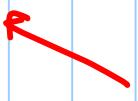
Path planning
with sensible
prob. distributions

Prob. "lossy"
Collins' decompt → hierarchical way of
or a
decomposing "C free" into cells and

determining adjacency relationships.

polynomial in geometric complexity

doubling exp. in dim. n of c-space
 2^{2^d}



Note: Can be reduced to 2^d via

using "matrix halving algorithm" which
halves a "vector map".

Alphprox. cell decomps:

- 1) Remarks give on a union of cells of pre-defined slope, often rectangulars. Generally hierarchical
- 2) easier to implement
- 3) provides more insight into the structure of tree
- 4) time + space complexity is exponential
dim of C-space. useful for low

\dim , often ≤ 4 .

General Structure:

See lecture 9a